

# Nonlinear Equations

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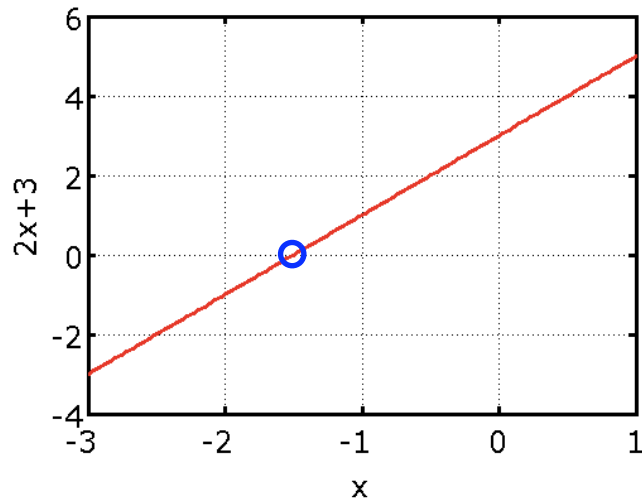
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# Linear vs. Nonlinear Equations

## Linear Equations

$$y = ax + b$$

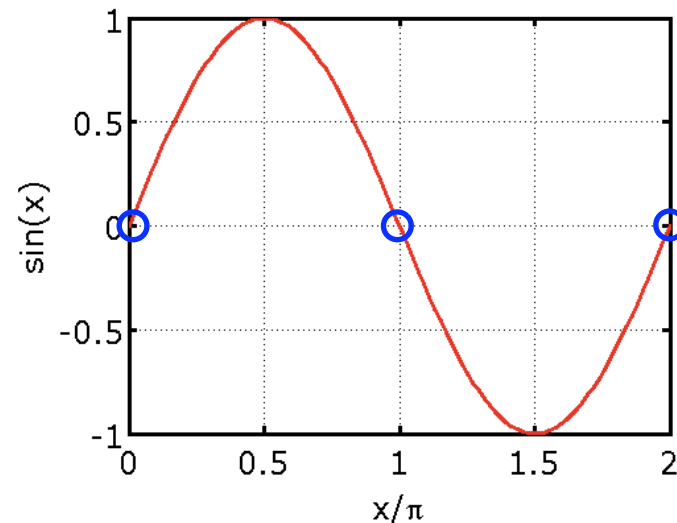
- Has a single, unique solution.
- Can be solved directly (analytically)



## Nonlinear Equations

$$y = \sin(x) \quad y = \sum_{i=1}^n a_i x^i$$

- May have 0...many solutions
- Sometimes cannot be solved analytically.
- Usually, numerical solutions are *iterative*, and require a *starting guess* for the solution.



# Polynomials

Any polynomial may be written as:  $p(x) = \sum_{i=0}^n a_i x^i$

Example:  $n=3$   $f(x) = \sum_{i=0}^3 a_i x^i = a_0 + a_1 x + a_2 x^2 + a_3 x^3$

## 📌 **roots (coef)**

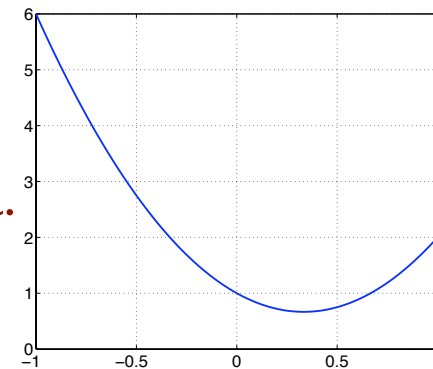
- provides ALL roots of the polynomial (even imaginary ones).

## 📌 **coef** - vector of length $n+1$ containing $a_i$ values in *descending* order

- coefficient of highest power is first ( $a_n$ )
- constant is last ( $a_0$ ).

**Example:** find the roots of  $y = 3x^2 - 2x + 1$   
Check your answer using the quadratic formula.

*What do we expect?*



# Single Nonlinear Equations - Excel

- Define a cell for  $x$ .
- Define a cell to calculate  $f(x)$ .
- Use Goal Seek (Tools → Goal Seek)
  - Choose the value you want to set the cell to (0)
  - Choose the cell that you want to change ( $x$ )

	A	B
1	x	$3x^2 - 2x - 1$
2	1	0

Goal Seek

Set cell:

To value:

By changing cell:

Cancel OK

Example: find the roots of  $y = 3x^2 - 2x + 1$

Example: find the roots of  $y = 3x^2 - 2x - 1$

Example: find the roots of  $f(x) = \sin(10x^3) \exp(-x^2)$

Use starting guess of 0.1, 0.35, 0.36, 0.75

# Single Nonlinear Equations - MATLAB

use for m-file  
functions

use for built in  
functions

use for anonymous  
functions

 `fzero('fun', xo)`   `fzero(@fun, xo)`   `fzero(f, xo)`

- Looks for the root (zero) of `fun` near `xo`.
- `fun` refers to a function that takes a value `x`, returns the function value,  $f(x)$ .
- `xo` is the starting guess for the solver.
- Can use this for nonlinear regression (could also use for linear regression...)

## Steps to Solve a Nonlinear Equation

1. Define the function you are to solve & write it in residual form  $f(x)=0$ .
2. Write a matlab function to calculate the value of  $f(x)$  given  $x$ .
3. Choose an initial guess as best as you can.
4. Use `fzero` to solve the problem.

# Functions with Parameters

$$y = x^a$$



```
function y = myfun(a,x)
y = x.^a;
```

What value of  $x$  gives  
 $y=5$  when  $a=-1.2$ ?

## 1. Create an “anonymous function”

- `tmpfun=@(x) (myfun(-1.2,x)-5)`
- Creates a new function called “`tmpfun`” that is only a function of  $x$ . This function calls `myfun` with  $a=-1.2$ .

## 2. Use `fzero` on this new function

- `xroot=fzero(tmpfun,1.0);`

```
clear; clc; close all;
a = -1.2;
```

```
% create an anonymous function using
% myfun with a=-1.2. Set up for use
% with a solver to determine where it
% is equal to 5.
```

```
tmpfun = @(x) (myfun(a,x)-5);
```

```
% determine the solution
xroot = fzero(tmpfun,1.0);
```

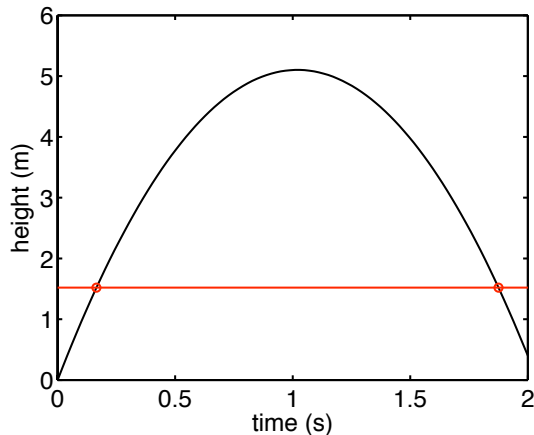
```
% plot the results
```

```
x = logspace(-2,1);
loglog(x,myfun(a,x),'k-', ...
       xroot,myfun(a,xroot),'ro', ...
       x,x*0.0+5,'r-');
```

```
% put the value of the root on the plot
text(xroot,10, strcat('x=' num2str(xroot)))
```

# Functions with Parameters

$$h = h_0 + v_0t + \frac{1}{2}at^2$$



```
function h = height_accelerate( ho, vo, a, t )  
h = ho + vo*t + 0.5*a*t.^2;
```

```
clear; clc; close all;
```

```
ho = 0.0; % initial height (m)  
vo = 10.0; % initial velocity (m/s)  
a = -9.8; % acceleration m/s^2  
h = 1.52; % find t when we are at this h
```

```
% Create a temporary function to use with  
% fsolve. We need to make a function that  
% has time as its only argument.
```

```
hsolve=@(t)(height_accelerate(ho,vo,a,t)-h);
```

```
t1 = fzero(hsolve,1.0);
```

```
t2 = fzero(hsolve,3.0);
```

```
% set the polynomial coefficients and  
% solve for roots of the polynomial
```

```
tt = roots( [a/2,vo,ho-h] )
```

**General Function:** find  $t$  to make  $r(t)=0$ .

$$r(t) = h_0 - h + v_0t + \frac{1}{2}at^2$$

**Polynomial:** find  $t$  to make  $p(t)=0$ .

$$p(t) = h_0 - h + v_0t + \frac{1}{2}at^2$$

# Functions with Parameters



$$\beta \equiv \frac{A}{LV_0} \left( 1 + \frac{V_0}{V_L} \right)$$

At  $z=0$ ,  $c_A$  is given by  $c_A = c_A^\infty + (c_A^0 - c_A^\infty) \exp(-\beta D_A(t - t_0))$

$c_A$  Concentration of "A" - mol/m<sup>3</sup>

$c_A^0$  Concentration of "A" at  $t=t_0$

$c_A^\infty$  Concentration of "A" at equilibrium ( $t \rightarrow \infty$ )

$D_A$  Diffusivity of "A" - m<sup>2</sup>/s

1. Create a function to calculate  $c_A$ .
2. Given  $\beta=0.01 \text{ m}^{-2}$ ,  $c_A^0=9 \text{ mol/m}^3$ ,  $c_A^\infty=1 \text{ mol/m}^3$ , and  $D_A=0.1 \text{ m}^2/\text{s}$ , when will  $c_A=2 \text{ mol/m}^3$ ?